

Second Edition

MOBILE ROBOTS



*Navigation, Control and Sensing,
Surface Robots and AUVs*

Gerald Cook
Feitian Zhang



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Mobile Robots Navigation Control And Remote Sensing

Georgi M. Dimirovski



Mobile Robots Navigation Control And Remote Sensing:

Mobile Robots Gerald Cook, Feitian Zhang, 2020-01-09 Presents the normal kinematic and dynamic equations for robots including mobile robots with coordinate transformations and various control strategies This fully updated edition examines the use of mobile robots for sensing objects of interest and focus primarily on control navigation and remote sensing It also includes an entirely new section on modeling and control of autonomous underwater vehicles AUVs which exhibits unique complex three dimensional dynamics Mobile Robots Navigation Control and Sensing Surface Robots and AUVs Second Edition starts with a chapter on kinematic models for mobile robots It then offers a detailed chapter on robot control examining several different configurations of mobile robots Following sections look at robot attitude and navigation The application of Kalman Filtering is covered Readers are also provided with a section on remote sensing and sensors Other chapters discuss target tracking including multiple targets with multiple sensors obstacle mapping and its application to robot navigation operating a robotic manipulator and remote sensing via UAVs The last two sections deal with the dynamics modeling of AUVs and control of AUVs In addition this text Includes two new chapters dealing with control of underwater vehicles Covers control schemes including linearization and use of linear control design methods Lyapunov stability theory and more Addresses the problem of ground registration of detected objects of interest given their pixel coordinates in the sensor frame Analyzes geo registration errors as a function of sensor precision and sensor pointing uncertainty Mobile Robots Navigation Control and Sensing Surface Robots and AUVs is intended for use as a textbook for a graduate course of the same title and can also serve as a reference book for practicing engineers working in related areas *Mobile Robots* Gerald Cook, 2011-10-14 An important feature of this book is the particular combination of topics included These are 1 control 2 navigation and 3 remote sensing all with application to mobile robots Much of the material is readily extended to any type ground vehicle In the controls area robot steering is the issue Both linear and nonlinear models are treated Various control schemes are utilized and through these applications the reader is introduced to methods such as 1 Linearization and use of linear control design methods for control about a reference trajectory 2 Use of Lyapunov stability theory for nonlinear control design 3 Derivation of optimal control strategies via Pontryagin's maximum principle 4 Derivation of a local coordinate system which is fundamental for the steering of vehicles along a path never before traversed This local coordinate system has application regardless of the control design methods utilized In the navigation area various coordinate systems are introduced and the transformations among them are derived 1 The Global Positioning System GPS is introduced and described in significant detail 2 Also introduced and discussed are inertial navigation systems INS These two methods are treated in terms of their ability to provide vehicle position as well as attitude A preceding chapter is devoted to coordinate rotations and transformations since they play an important role in the understanding of this body of theory **Modeling and Control of a Tracked Mobile Robot for Pipeline Inspection** Michał Ciszewski, Mariusz Giergiel, Tomasz

Buratowski, Piotr Małka, 2020-03-18 This book describes the design mathematical modeling control system development and experimental validation of a versatile mobile pipe inspection robot It also discusses a versatile robotic system for pipeline inspection together with an original adaptable tracked mobile robot featuring a patented motion unit Pipeline inspection is a common field of application for mobile robots because the monitoring of inaccessible long and narrow pipelines is a very difficult task for humans The main design objective is to minimize the number of robots needed to inspect different types of horizontal and vertical pipelines with both smooth and rough surfaces The book includes extensive information on the various design phases mathematical modeling simulations and control system development In closing the prototype construction process and testing procedures are presented and supplemented with laboratory and field experiments Fuzzy Systems and Data Mining V

Antonio J. Tallón-Ballesteros, 2019-11-15 The Fuzzy Systems and Data Mining FSDM conference is an annual event encompassing four main themes fuzzy theory algorithms and systems which includes topics like stability foundations and control fuzzy application which covers different kinds of processing as well as hardware and architectures for big data and time series and has wide applicability the interdisciplinary field of fuzzy logic and data mining encompassing applications in electrical industrial chemical and engineering fields as well as management and environmental issues and data mining outlining new approaches to big data massive data scalable parallel and distributed algorithms The annual conference provides a platform for knowledge exchange between international experts researchers academics and delegates from industry This book includes the papers accepted and presented at the 5th International Conference on Fuzzy Systems and Data Mining FSDM 2019 held in Kitakyushu Japan on 18 21 October 2019 This year FSDM received 442 submissions All papers were carefully reviewed by program committee members taking account of the quality novelty soundness breadth and depth of the research topics falling within the scope of FSDM The committee finally decided to accept 137 papers which represents an acceptance rate of about 30% The papers presented here are arranged in two sections Fuzzy Sets and Data Mining and Communications and Networks Providing an overview of the most recent scientific and technological advances in the fields of fuzzy systems and data mining the book will be of interest to all those working in these fields Complex Systems

Georgi M. Dimirovski, 2016-05-19 This book gives a wide ranging description of the many facets of complex dynamic networks and systems within an infrastructure provided by integrated control and supervision envisioning design experimental exploration and implementation The theoretical contributions and the case studies presented can reach control goals beyond those of stabilization and output regulation or even of adaptive control Reporting on work of the Control of Complex Systems COSY research program Complex Systems follows from and expands upon an earlier collection Control of Complex Systems by introducing novel theoretical techniques for hard to control networks and systems The major common feature of all the superficially diverse contributions encompassed by this book is that of spotting and exploiting possible areas of mutual reinforcement between control computing and communications These help readers to achieve not only robust

stable plant system operation but also properties such as collective adaptivity integrity and survivability at the same time retaining desired performance quality Applications in the individual chapters are drawn from the general implementation of model based diagnosis and systems engineering in medical technology in communication and in power and airport networks the creation of biologically inspired control brains and safety critical human machine systems process industrial uses biped robots large space structures and unmanned aerial vehicles and precision servomechanisms and other advanced technologies Complex Systems provides researchers from engineering applied mathematics and computer science backgrounds with innovative theoretical and practical insights into the state of the art of complex networks and systems research It employs physical implementations and extensive computer simulations Graduate students specializing in complex systems research will also learn much from this collection pp

Proceedings of the International Conference on Intelligent Vision and Computing (ICIVC 2021) Harish Sharma,Vijay Kumar Vyas,Rajesh Kumar Pandey,Mukesh Prasad,2022-03-23 This book gathers outstanding research papers presented at the International Conference on Intelligent Vision and Computing ICIVC 2021 held online during October 03 04 2021 ICIVC 2021 is organised by Sur University Oman The book presents novel contributions in intelligent vision and computing and serves as reference material for beginners and advanced research The topics covered are intelligent systems intelligent data analytics and computing intelligent vision and applications collective intelligence soft computing optimization cloud computing machine learning intelligent software robotics data science data security big data analytics and signal natural language processing *Interactive Collaborative Robotics* Andrey Ronzhin, Gerhard Rigoll, Roman Meshcheryakov, 2018-09-10 This book constitutes the proceedings of the Third International Conference on Interactive Collaborative Robotics ICR 2018 held in Leipzig Germany in September 2018 as a satellite event of the 20th International Conference on Speech and Computer SPECOM 2018 The 30 papers presented in this volume were carefully reviewed and selected from 51 submissions The papers presents challenges of human robot interaction robot control and behavior in social robotics and collaborative robotics as well as applied robotic and cyberphysical systems

Advances in Asian Mechanism and Machine Science Nguyen Van Khang, Nguyen Quang Hoang, Marco Ceccarelli, 2021-12-14 This book presents the proceedings of the 6th IFToMM Asian Mechanisms and Machine Science Conference Asian MMS held in Hanoi Vietnam on December 15 18 2021 It includes peer reviewed papers on the latest advances in mechanism and machine science discussing topics such as biomechanical engineering computational kinematics the history of mechanism and machine science gearing and transmissions multi body dynamics robotics and mechatronics the dynamics of machinery tribology vibrations rotor dynamics and vehicle dynamics A valuable up to date resource it offers an essential overview of the subject for scientists and practitioners alike and will inspire further investigations and research

Decentralized Neural Control: Application to Robotics Ramon Garcia-Hernandez, Michel Lopez-Franco, Edgar N. Sanchez, Alma y. Alanis, Jose A. Ruz-Hernandez, 2017-02-05 This book provides a decentralized approach for the identification

and control of robotics systems It also presents recent research in decentralized neural control and includes applications to robotics Decentralized control is free from difficulties due to complexity in design debugging data gathering and storage requirements making it preferable for interconnected systems Furthermore as opposed to the centralized approach it can be implemented with parallel processors This approach deals with four decentralized control schemes which are able to identify the robot dynamics The training of each neural network is performed on line using an extended Kalman filter EKF The first indirect decentralized control scheme applies the discrete time block control approach to formulate a nonlinear sliding manifold The second direct decentralized neural control scheme is based on the backstepping technique approximated by a high order neural network The third control scheme applies a decentralized neural inverse optimal control for stabilization The fourth decentralized neural inverse optimal control is designed for trajectory tracking This comprehensive work on decentralized control of robot manipulators and mobile robots is intended for professors students and professionals wanting to understand and apply advanced knowledge in their field of work Intelligent Control of Robotic Systems Laxmidhar Behera,Swagat Kumar,Prem Kumar Patchaikani,Ranjith Ravindranathan Nair,Samrat Dutta,2020-04-07 This book illustrates basic principles along with the development of the advanced algorithms to realize smart robotic systems It speaks to strategies by which a robot manipulators mobile robot quadrotor can learn its own kinematics and dynamics from data In this context two major issues have been dealt with namely stability of the systems and experimental validations Learning algorithms and techniques as covered in this book easily extend to other robotic systems as well The book contains MATLAB based examples and c codes under robot operating systems ROS for experimental validation so that readers can replicate these algorithms in robotics platforms

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