Rethinking Quaternions

Theory and Computation

Ron Goldman

Synthesis Lectures on Computer Graphics and Animation

Veronica Sundstedt

Rethinking Quaternions Ron Goldman, 2022-05-31 Quaternion multiplication can be used to rotate vectors in three dimensions Therefore in computer graphics quaternions have three principal applications to increase speed and reduce storage for calculations involving rotations to avoid distortions arising from numerical inaccuracies caused by floating point computations with rotations and to interpolate between two rotations for key frame animation Yet while the formal algebra of quaternions is well known in the graphics community the derivations of the formulas for this algebra and the geometric principles underlying this algebra are not well understood The goals of this monograph are to provide a fresh geometric interpretation for guaternions appropriate for contemporary computer graphics based on mass points to present better ways to visualize quaternions and the effect of quaternion multiplication on points and vectors in three dimensions using insights from the algebra and geometry of multiplication in the complex plane to derive the formula for guaternion multiplication from first principles to develop simple intuitive proofs of the sandwiching formulas for rotation and reflection to show how to apply sandwiching to compute perspective projections In addition to these theoretical issues we also address some computational questions We develop straightforward formulas for converting back and forth between quaternion and matrix representations for rotations reflections and perspective projections and we discuss the relative advantages and disadvantages of the quaternion and matrix representations for these transformations Moreover we show how to avoid distortions due to floating point computations with rotations by using unit quaternions to represent rotations We also derive the formula for spherical linear interpolation and we explain how to apply this formula to interpolate between two rotations for key frame animation Finally we explain the role of quaternions in low dimensional Clifford algebras and we show how to apply the Clifford algebra for R3 to model rotations reflections and perspective projections To help the reader understand the concepts and formulas presented here we have incorporated many exercises in order to clarify and elaborate some of the key points in the text Table of Contents Preface Theory Computation Rethinking Quaternions and Clif ford Algebras References Further Reading Author Biography Rethinking Quaternions Ron Goldman, 2010-05-05 Quaternion multiplication can be used to rotate vectors in three dimensions Therefore in computer graphics quaternions have three principal applications to increase speed and reduce storage for calculations involving rotations to avoid distortions arising from numerical inaccuracies caused by floating point computations with rotations and to interpolate between two rotations for key frame animation Yet while the formal algebra of quaternions is well known in the graphics community the derivations of the formulas for this algebra and the geometric principles underlying this algebra are not well understood The goals of this monograph are to provide a fresh geometric interpretation for quaternions appropriate for contemporary computer graphics based on mass points to present better ways to visualize quaternions and the effect of quaternion multiplication on points and vectors in three dimensions using insights from the algebra and geometry of multiplication in the complex plane to derive the

formula for quaternion multiplication from first principles to develop simple intuitive proofs of the sandwiching formulas for rotation and reflection to show how to apply sandwiching to compute perspective projections In addition to these theoretical issues we also address some computational questions We develop straightforward formulas for converting back and forth between quaternion and matrix representations for rotations reflections and perspective projections and we discuss the relative advantages and disadvantages of the quaternion and matrix representations for these transformations Moreover we show how to avoid distortions due to floating point computations with rotations by using unit quaternions to represent rotations We also derive the formula for spherical linear interpolation and we explain how to apply this formula to interpolate between two rotations for key frame animation Finally we explain the role of quaternions in low dimensional Clifford algebras and we show how to apply the Clifford algebra for R3 to model rotations reflections and perspective projections To help the reader understand the concepts and formulas presented here we have incorporated many exercises in order to clarify and elaborate some of the key points in the text Table of Contents Preface Theory Computation Rethinking Quaternions and Clif ford Algebras References Further Reading Author Biography <u>Dual Quaternions and Their Associated Clifford Algebras</u> Ronald Goldman, 2023-09-29 Clifford algebra for dual quaternions has emerged recently as an alternative to standard matrix algebra as a computational framework for computer graphics This book presents dual quaternions and their associated Clifford algebras in a new light accessible to and geared toward the computer graphics community Collecting all the associated formulas and theorems in one place this book provides an extensive and rigorous treatment of dual quaternions as well as showing how two models of Clifford algebra emerge naturally from the theory of dual quaternions Each section comes complete with a set of exercises to help readers sharpen and practice their understanding This book is accessible to anyone with a basic knowledge of quaternion algebra and is of particular use to forward thinking members of the computer graphics Advances in Imaging and Electron Physics, 2013-01-17 Advances in Imaging and Electron Physics features community cutting edge articles on the physics of electron devices especially semiconductor devices particle optics at high and low energies microlithography image science and digital image processing electromagnetic wave propagation electron microscopy and the computing methods used in all these domains Contributions from leading authorities Informs and updates on all the latest developments in the field **Information Theory Tools for Image Processing Miguel** Feixas, Anton Bardera, Jaume Rigau, Qing Xu, 2022-06-01 Information Theory IT tools widely used in many scientific fields such as engineering physics genetics neuroscience and many others are also useful transversal tools in image processing In this book we present the basic concepts of IT and how they have been used in the image processing areas of registration segmentation video processing and computational aesthetics Some of the approaches presented such as the application of mutual information to registration are the state of the art in the field All techniques presented in this book have been previously published in peer reviewed conference proceedings or international journals We have stressed here their common

aspects and presented them in an unified way so to make clear to the reader which problems IT tools can help to solve which specific tools to use and how to apply them The IT basics are presented so as to be self contained in the book The intended audiences are students and practitioners of image processing and related areas such as computer graphics and visualization In addition students and practitioners of IT will be interested in knowing about these applications Table of Contents Preface Acknowledgments Information Theory Basics Image Registration Image Segmentation Video Key Frame Selection Informational Aesthetics Measures Bibliography Authors Biographies **Numerical Methods for Linear** Complementarity Problems in Physics-Based Animation Sarah Niebe, Kenny Erleben, 2022-05-31 Linear complementarity problems LCPs have for many years been used in physics based animation to model contact forces between rigid bodies in contact More recently LCPs have found their way into the realm of fluid dynamics Here LCPs are used to model boundary conditions with fluid wall contacts LCPs have also started to appear in deformable models and granular simulations There is an increasing need for numerical methods to solve the resulting LCPs with all these new applications This book provides a numerical foundation for such methods especially suited for use in computer graphics This book is mainly intended for a researcher Ph D student post doc professor who wants to study the algorithms and do more work research in this area Programmers might have to invest some time brushing up on math skills for this we refer to Appendices A and B The reader should be familiar with linear algebra and differential calculus We provide pseudo code for all the numerical methods which should be comprehensible by any computer scientist with rudimentary programming skills The reader can find an online supplementary code repository containing Matlab implementations of many of the core methods covered in these notes as well as a few Python implementations Erleben 2011 Table of Contents Introduction Numerical Methods Guide for Software and Selecting Methods Bibliography Authors Biographies Gazing at Games Veronica Sundstedt, 2022-05-31 Eye tracking is a process that identifies a specific point in both space and time that is being looked at by the observer This information can also be used in real time to control applications using the eyes Recent innovations in the video game industry include alternative input modalities to provide an enhanced more immersive user experience In particular eye gaze control has recently been explored as an input modality in video games This book is an introduction for those interested in using eye tracking to control or analyze video games and virtual environments Key concepts are illustrated through three case studies in which gaze control and voice recognition have been used in combination to control virtual characters and applications The lessons learned in the case studies are presented and issues relating to incorporating eye tracking in interactive applications are discussed The reader will be given an introduction to human visual attention eye movements and eye tracking technologies Previous work in the field of studying fixation behavior in games and using eye tracking for video game interaction will also be presented The final chapter discusses ideas for how this field can be developed further to create richer interaction for characters and crowds in virtual environments Alternative means of

interaction in video games are especially important for disabled users for whom traditional techniques such as mouse and keyboard may be far from ideal This book is also relevant for those wishing to use gaze control in applications other than games Table of Contents Introduction The Human Visual System Eye Tracking Eye Tracking in Video Games Gaze and Voice Controlled Video Games Case Study I and II Gaze and Voice Controlled Drawing Case Study III Conclusion

Mathematical Tools for Shape Analysis and Description Silvia Biasotti, Bianca Falcidieno, Daniela Giorgi, Michela Spagnuolo, 2022-06-01 This book is a guide for researchers and practitioners to the new frontiers of 3D shape analysis and the complex mathematical tools most methods rely on The target reader includes students researchers and professionals with an undergraduate mathematics background who wish to understand the mathematics behind shape analysis The authors begin with a guick review of basic concepts in geometry topology differential geometry and proceed to advanced notions of algebraic topology always keeping an eye on the application of the theory through examples of shape analysis methods such as 3D segmentation correspondence and retrieval A number of research solutions in the field come from advances in pure and applied mathematics as well as from the re reading of classical theories and their adaptation to the discrete setting In a world where disciplines fortunately have blurred boundaries the authors believe that this guide will help to bridge the distance between theory and practice Table of Contents Acknowledgments Figure Credits About this Book 3D Shape Analysis in a Nutshell Geometry Topology and Shape Representation Differential Geometry and Shape Analysis Spectral Methods for Shape Analysis Maps and Distances between Spaces Algebraic Topology and Topology Invariants Differential Topology and Shape Analysis Reeb Graphs Morse and Morse Smale Complexes Topological Persistence Beyond Geometry and Topology Resources Bibliography Authors Biographies Efficient Quadrature Rules for Illumination Integrals Ricardo Margues, Christian Bouville, Luís Paulo Santos, Kadi Bouatouch, 2022-06-01 Rendering photorealistic images is a costly process which can take up to several days in the case of high quality images In most cases the task of sampling the incident radiance function to evaluate the illumination integral is responsible for an important share of the computation time Therefore to reach acceptable rendering times the illumination integral must be evaluated using a limited set of samples Such a restriction raises the question of how to obtain the most accurate approximation possible with such a limited set of samples One must thus ensure that sampling produces the highest amount of information possible by carefully placing and weighting the limited set of samples Furthermore the integral evaluation should take into account not only the information brought by sampling but also possible information available prior to sampling such as the integrand smoothness This idea of sparse information and the need to fully exploit the little information available is present throughout this book The presented methods correspond to the state of the art solutions in computer graphics and take into account information which had so far been underexploited or even neglected by the previous approaches The intended audiences are Ph D students and researchers in the field of realistic image synthesis or global illumination algorithms or any person with a solid background in graphics and numerical techniques
Quaternions for Computer Graphics John Vince, 2021-09-02 If you have ever wondered what quaternions are then look no further John Vince will show you how simple and useful they are This 2nd edition has been completely revised and includes extra detail on the invention of quaternions a complete review of the text and equations all figures are in colour extra worked examples an expanded index and a bibliography arranged for each chapter Quaternions for Computer Graphics includes chapters on number sets and algebra imaginary and complex numbers the complex plane rotation transforms and a comprehensive description of quaternions in the context of rotation The book will appeal to students of computer graphics computer science and mathematics as well as programmers researchers academics and professional practitioners interested in learning about quaternions John Vince explains in an easy to understand language with the aid of useful figures how quaternions emerged gave birth to modern vector analysis disappeared and reemerged to be adopted by the flight simulation industry and computer graphics This book will give you the confidence to use quaternions within your every day mathematics and explore more advanced texts

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