

Systems & Control: Foundations & Applications

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Output Regulation of Uncertain Nonlinear Systems



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Output Regulation Of Uncertain Nonlinear Systems Systems Control Foundations Applications

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Output Regulation of Uncertain Nonlinear Systems Christopher I. Byrnes, Francesco Delli Priscoli, Alberto Isidori, 2012-12-06 The problem of controlling the output of a system so as to achieve asymptotic tracking of prescribed trajectories and or asymptotic rejection of undesired disturbances is a central problem in control theory A classical setup in which the problem was posed and successfully addressed in the context of linear time invariant and finite dimensional systems is the one in which the exogenous inputs namely commands and disturbances may range over the set of all possible trajectories of a given autonomous linear system commonly known as the exogenous system or more the exosystem The case when the exogenous system is a harmonic oscillator is of course classical Even in this special case the difference between state and error measurement feedback in the problem of output regulation is profound To know the initial condition of the exosystem is to know the amplitude and phase of the corresponding sinusoid On the other hand to solve the output regulation problem in this case with only error measurement feedback is to track or attenuate a sinusoid of known frequency but with unknown amplitude and phase This is in sharp contrast with alternative approaches such as exact output tracking where in lieu of the assumption that a signal is within a class of signals generated by an exogenous system one instead assumes complete knowledge of the past present and future time history of the trajectory to be tracked

Output Regulation of Uncertain Nonlinear Systems Christopher I. Byrnes, Francesco Delli Priscoli, Alberto Isidori, 1997-06 The problem of controlling the output of a system so as to achieve asymptotic tracking of prescribed trajectories and or asymptotic rejection of undesired disturbances is a central problem in control theory A classical setup in which the problem was posed and successfully addressed in the context of linear time invariant and finite dimensional systems is the one in which the exogenous inputs namely commands and disturbances may range over the set of all possible trajectories of a given autonomous linear system commonly known as the exogenous system or more the exosystem The case when the exogenous system is a harmonic oscillator is of course classical Even in this special case the difference between state and error measurement feedback in the problem of output regulation is profound To know the initial condition of the exosystem is to know the amplitude and phase of the corresponding sinusoid On the other hand to solve the output regulation problem in this case with only error measurement feedback is to track or attenuate a sinusoid of known frequency but with unknown amplitude and phase This is in sharp contrast with alternative approaches such as exact output tracking where in lieu of the assumption that a signal is within a class of signals generated by an exogenous system one instead assumes complete knowledge of the past present and future time history of the trajectory to be tracked

Stabilization and Regulation of Nonlinear Systems Zhiyong Chen, Jie Huang, 2014-08-30 The core of this textbook is a systematic and self contained treatment of the nonlinear stabilization and output regulation problems Its coverage embraces both fundamental concepts and advanced research outcomes and includes many numerical and practical examples Several classes of important

uncertain nonlinear systems are discussed The state of the art solution presented uses robust and adaptive control design ideas in an integrated approach which demonstrates connections between global stabilization and global output regulation allowing both to be treated as stabilization problems Stabilization and Regulation of Nonlinear Systems takes advantage of rich new results to give students up to date instruction in the central design problems of nonlinear control problems which are a driving force behind the furtherance of modern control theory and its application The diversity of systems in which stabilization and output regulation become significant concerns in the mathematical formulation of practical control solutions whether in disturbance rejection in flying vehicles or synchronization of Lorenz systems with harmonic systems makes the text relevant to readers from a wide variety of backgrounds Many exercises are provided to facilitate study and solutions are freely available to instructors via a download from springerextras.com Striking a balance between rigorous mathematical treatment and engineering practicality Stabilization and Regulation of Nonlinear Systems is an ideal text for graduate students from many engineering and applied mathematical disciplines seeking a contemporary course in nonlinear control Practitioners and academic theorists will also find this book a useful reference on recent thinking in this field *Nonlinear Output Regulation* Jie Huang, 2004-11-01 This book provides a comprehensive and in depth treatment of the nonlinear output regulation problem **Stability and Stabilization** William J. Terrell, 2009-02-15 Stability and Stabilization is the first intermediate level textbook that covers stability and stabilization of equilibria for both linear and nonlinear time invariant systems of ordinary differential equations Designed for advanced undergraduates and beginning graduate students in the sciences engineering and mathematics the book takes a unique modern approach that bridges the gap between linear and nonlinear systems Presenting stability and stabilization of equilibria as a core problem of mathematical control theory the book emphasizes the subject's mathematical coherence and unity and it introduces and develops many of the core concepts of systems and control theory There are five chapters on linear systems and nine chapters on nonlinear systems an introductory chapter a mathematical background chapter a short final chapter on further reading and appendixes on basic analysis ordinary differential equations manifolds and the Frobenius theorem and comparison functions and their use in differential equations The introduction to linear system theory presents the full framework of basic state space theory providing just enough detail to prepare students for the material on nonlinear systems Focuses on stability and feedback stabilization Bridges the gap between linear and nonlinear systems for advanced undergraduates and beginning graduate students Balances coverage of linear and nonlinear systems Covers cascade systems Includes many examples and exercises

From Static to Dynamic Couplings in Consensus and Synchronization Among Identical and Non-Identical Systems Peter Wieland, 2010 In a systems theoretic context the terms consensus and synchronization both describe the property that all individual systems in a group behave asymptotically identical i.e. output or state trajectories asymptotically converge to a common trajectory The objective of the present thesis is an improved understanding of some of the diverse

coupling mechanisms leading to consensus and synchronization A starting point is the observation that classical consensus and synchronization results commonly deal with two distinct facets of the problem Consensus has regularly a strong focus on the interconnections and related constraints while synchronization typically addresses questions about complex individual dynamical systems Very few results exist that address both facets simultaneously A thorough analysis of static couplings in consensus algorithms provides explanations for this observation by unveiling limitations inherent to this type of couplings Novel dynamic coupling mechanisms are proposed to overcome these limitations These methods essentially rely on an internal model principle for consensus and synchronization derived in the thesis This principle provides necessary conditions for consensus and synchronization in groups of non identical systems and it establishes a link to the output regulation problem The fresh point of view revealed by this link eventually leads to a new hierarchical mechanism for consensus and synchronization among complex non identical systems with weak assumptions on the interconnections Applications include synchronization of linear systems and phase synchronization of nonlinear oscillators

Nonlinear Control of Dynamic Networks Tengfei Liu,Zhong-Ping Jiang,David J. Hill,2018-09-03 Significant progress has been made on nonlinear control systems in the past two decades However many of the existing nonlinear control methods cannot be readily used to cope with communication and networking issues without nontrivial modifications For example small quantization errors may cause the performance of a well designed nonlinear control system to deteriorate Motivated by the need for new tools to solve complex problems resulting from smart power grids biological processes distributed computing networks transportation networks robotic systems and other cutting edge control applications Nonlinear Control of Dynamic Networks tackles newly arising theoretical and real world challenges for stability analysis and control design including nonlinearity dimensionality uncertainty and information constraints as well as behaviors stemming from quantization data sampling and impulses Delivering a systematic review of the nonlinear small gain theorems the text Supplies novel cyclic small gain theorems for large scale nonlinear dynamic networks Offers a cyclic small gain framework for nonlinear control with static or dynamic quantization Contains a combination of cyclic small gain and set valued map designs for robust control of nonlinear uncertain systems subject to sensor noise Presents a cyclic small gain result in directed graphs and distributed control of nonlinear multi agent systems with fixed or dynamically changing topology Based on the authors recent research Nonlinear Control of Dynamic Networks provides a unified framework for robust quantized and distributed control under information constraints Suggesting avenues for further exploration the book encourages readers to take into consideration more communication and networking issues in control designs to better handle the arising challenges

Partially Observable Linear Systems Under Dependent Noises Agamirza E. Bashirov,2003-01-23 This book discusses the methods of fighting against noise It can be regarded as a mathematical view of specific engineering problems with known and new methods of control and estimation in noisy media From the reviews An excellent reference on the complete sets of equations for the optimal controls and for the

optimal filters under wide band noises and shifted white noises and their possible application to navigation of spacecraft
MATHEMATICAL REVIEWS **Dynamical Systems, Control, Coding, Computer Vision** Giorgio Picci,D.S.

Gilliam,2012-12-06 This book is a collection of essays devoted in part to new research directions in systems networks and control theory and in part to the growing interaction of these disciplines with new sectors of engineering and applied sciences like coding computer vision and hybrid systems These are new areas of rapid growth and of increasing importance in modern technology The essays written by world leading experts in the field reproduce and expand the plenary and minicoursejminisymposia invited lectures which were delivered at the Mathematical Theory of Networks and Systems Symposium MTNS 98 held in Padova Italy on July 6 10 1998 Systems control and networks theory has permeated the development of much of present day technology The impact has been visible in the past fifty years through the dramatic expansion and achievements of the aerospace and avionics industry through process control and factory automation robotics communication signals analysis and synthesis and more recently even finance to name just the most visible applications The theory has developed from the early phase of its history when the basic tools were elementary complex analysis Laplace transform and linear differential equations to present day where the mathematics ranges widely from functional analysis PDEs abstract algebra stochastic processes and differential geometry Irrespective of the particular tools however the basic unifying paradigms of feedback stability optimal control and recursive filtering have remained the bulk of the field and continue to be the basic motivation for the theory coming from the real world Advances in Statistical Control, Algebraic

Systems Theory, and Dynamic Systems Characteristics Chang-Hee Won,Cheryl B. Schrader,Anthony N. Michel,2010-07-08 Life has many surprises One of the best surprises is meeting a caring mentor an encouraging collaborator or an enthusiastic friend This volume is a tribute to Professor Michael K Sain who is such a teacher colleague and friend On the beautiful fall day of October 27 2007 friends families colleagues and former students gathered at a workshop held in Notre Dame Indiana This workshop brought together many people whose lives have been touched by Mike to celebrate his milestone 70th birthday and to congratulate him on his contributions in the fields of systems circuits and control Mike was born on March 22 1937 in St Louis Missouri After obtaining his B S E E and M S E E at St Louis University he went on to study at the University of Illinois at Urbana Champaign for his doctoral degree With his Ph D degree complete he came to the University of Notre Dame in 1965 as an assistant professor He became an associate professor in 1968 a full professor in 1972 and the Frank M Freimann Chair in Electrical Engineering in 1982 He has remained at and loved the University of Notre Dame for over 40 years Mike also held a number of consulting jobs throughout his career Most notably he consulted with the Energy Controls Division of Allied Bendix Aerospace from 1976 to 1988 and the North American Operations branch of the Research and Development Laboratory of General Motors Corporation for a decade 1984 1994

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